

V-Edge: Virtual Edge Computing as an Enabler for Novel Microservices and Cooperative Computing

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Abstract—As we move from 5G to 6G, edge computing is one of the concepts that needs revisiting. Its core idea is still intriguing: instead of sending all data and tasks from an end user’s device to the cloud, possibly covering thousands of kilometers and introducing delays that are just owed to limited propagation speed, edge servers deployed in close proximity to the user, e.g., at some 5G gNB, serve as proxy for the cloud. Yet this promising idea is hampered by the limited availability of such edge servers. In this paper, we discuss a way forward, namely the virtual edge computing (V-Edge) concept. V-Edge bridges the gap between cloud, edge, and fog by virtualizing all available resources including the end users’ devices and making these resources widely available using well-defined interfaces. V-Edge also acts as an enabler for novel microservices as well as cooperative computing solutions. We introduce the general V-Edge architecture and we characterize some of the key research challenges to overcome, in order to enable wide-spread and even more powerful edge services.

I. INTRODUCTION

New-generation mobile networks are envisioned to provide the computational, memory, and storage resources needed to run services required by diverse third parties (referred to as vertical industries or verticals). Each service is associated with specific requirements, quantified as key performance indicators (KPIs). To this end, networks will require a high degree of flexibility and fully automated operations, with a drastically reduced service deployment time. Essential components to

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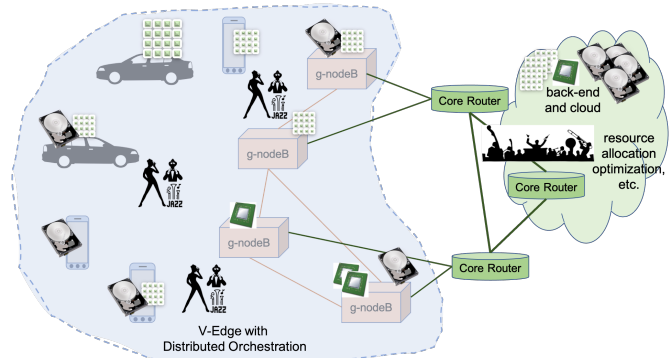


Figure 1. The V-Edge concept: Abstraction of the physical resources of the cloud back-end, the 5G core and RAN, as well as users and machines. All components provide (and may use) resources for edge computing and they may participate in a local, distributed orchestration on short time-scale, while global optimization and other non-real-time operations can be performed in the cloud back-end.

achieve these goals are softwarization of both networking and services using network function virtualization (NFV) [1]–[3] and the ability to store and process data close to the end user leveraging the so-called edge computing paradigm [4]. Note that edge computing is not just about classic multi-access edge computing (MEC) [4], [5]; rather, the network edge has become the convergence point of data processing, caching, and communication [6], which makes service provisioning at the edge one of the key challenges in future networks.

Network virtualization, greatly supported by the current 5G/6G standardization and research beyond it, pushes NFV to merge with the concept of microservices to improve practicality, universality, and automation. Service ubiquity, resilience, and low latency are emerging as the ultimate goals – following up the recent work in the context of the Tactile Internet [7], [8]. To achieve these goals, networks are progressively integrating machine learning (ML) [9] in two main ways. First, an increasing number of user applications include ML models for a smarter application behavior, higher ability to adapt to user’s preferences, and more effective interaction between users and machines. Second, ML-based approaches have become common in automatic network management, resource orchestration, as well as predicting a wide range of parameters (e.g., wireless channel properties, users’ behavior, service demand).

Given these emerging trends, *the network edge is turning into an enabler* between the cloud and a fully-distributed machine-to-machine (M2M) network, hosting virtualized network functions and user applications, to meet both service providers’ and users’ needs.

Table I
TYPICAL NODES PARTICIPATING IN V-EDGE CLUSTERS

Stationary / infrastructure-based systems				
Type	CPU	Storage	Network	Time available
ISP-operated MEC server	high-performance multi-core	1 – 100 TB	0.1 – 10 Gbit/s	years
privately operated MEC server	multi-core	1 – 10 TB	0.1 – 1 Gbit/s	weeks
Wi-Fi APs	single core	0.1 – 100 GB	0.1 – 1 Gbit/s	months
Mobile / opportunistic systems				
Type	CPU	Storage	Network	Time available
Moving car	low-end multi-core	0.1 – 1 TB	0.1 – 1 Gbit/s	1 – 5 min
Parked car	low-end multi-core	0.1 – 1 TB	0.1 – 1 Gbit/s	0.5 – 24 h
Fully autonomous shuttle	high-performance multi-core	1 – 10 TB	0.1 – 1 Gbit/s	1 – 30 min
User with smartphone	single- to multi-core	1 – 100 GB	0.1 – 1 Gbit/s	5 – 15 min

This work introduces the *virtual edge computing (V-Edge)* concept. It takes advantage of the flexibility offered by network softwarization and NFV to integrate in an opportunistic and dynamic manner the highly heterogeneous set of resources available locally at the edge (e.g., computing, storage, and communication resources), while guaranteeing seamless and QoS-aware service provisioning to users in a variety of verticals. Further, it jointly uses such resources for any virtualized function of a user application.

A schematic representation of the V-Edge concept is depicted in Figure 1. Compared to 5G and traditional edge computing, the system comprises dynamic resources: CPUs, connectivity, and storage capacity come and go as users do, carrying the corresponding devices. Thus, we have to move from allocating *static* resources to dynamic users and applications to allocating resources that are dynamic as well. An example is the integration of cars not only as service users, but also as service providers such as explored in the vehicular micro-cloud concept [10]. V-Edge goes well beyond initial activities towards distributed computing and data storage, realizing a full and harmonic integration between infrastructure-based communication networks and mobile edge systems at the resource level, as well as between user applications and network functions at the service layer.

In V-Edge, part of the orchestration of resources and tasks needs to be done at the edge on rather short time scales to cope with resource volatility and dynamics. The back-end cloud, instead, can be used for global optimization on longer time scales. Following current ML approaches to 5G and edge computing [9], V-Edge will also be inherently learning-based, supporting both user applications and network functions. V-Edge can implement privacy-preserving, distributed approaches such as federated learning [11]) and effectively transfer trained model where and as needed.

Our main contributions can be summarized as follows:

- we characterize the need to go beyond classic MEC for higher scalability, resilience, and flexibility;
- we introduce the conceptual architecture of V-Edge making consequent use of virtualization to deal with the high degree of dynamics in the network; and
- we discuss relevant research questions to be solved to make V-Edge reality.

II. THE V-EDGE ECOSYSTEM

Before outlining the virtual edge computing architecture, we introduce the underlying basic components of the V-Edge eco-system, including the major services it can support.

a) Users: As in conventional systems, users still contribute to the traffic demand while using edge-based applications. In V-Edge, users may have a dual representation in the system as edge users but also as resource providers.

b) Resources: The resources to satisfy the user demand, network-wise and application-wise, are now provided by an increasing variety of devices ranging from the cloud to ISP-operated edge servers, and even to community-operated edge devices and to smaller IoT systems. V-Edge thus goes well beyond classic MEC, by dropping the differentiation between cloud and edge and fog, and opportunistically recruiting local, already existing – yet possibly unused – resources. In V-Edge, even small “fog” devices are conceptually turned into “edge servers” to provide functions to third parties. A list of typical V-Edge computational, storage, and networking resources is provided in Table I, which also indicates the average time each kind of edge node will be available in a given location. This results in dynamic scenarios – classic MEC assumes dynamics in terms of users and their tasks coming and going. Now, also the available edge computing resources come and go in a very dynamic way, and they can be seen as constituting a *virtualized edge server* with time-varying resource availability.

c) Services and Functions: Network services, and often user applications, need to be deployed within the V-Edge. The classes of user applications that can benefit most from a virtual edge implementation are:

- services with tight latency constraints or whose support with dedicated static infrastructure would have brought too high CAPEX, e.g., cooperative (automated) driving and UAV control, in need of capillary local edge support even out of cities;
- services that may exhibit bursts of demand of computing tasks, e.g., due to “flash crowds”;
- non-latency-constrained applications such as computing tasks for situation awareness, distributed video processing, and event detection;
- internet of things (IoT) applications like monitoring tasks, where local data have to be pre-processed for immediate

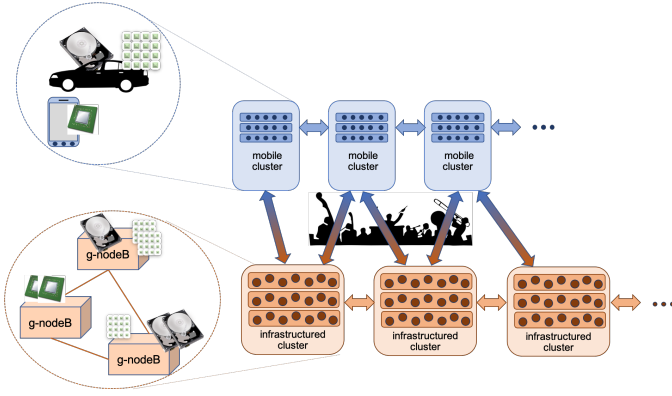


Figure 2. V-Edge architecture: Logical resources from mobile users and infrastructure-based systems (e.g., edge servers co-located with a gNB), are aggregated into clusters. Multiple clusters are appropriately coordinated and microservices can migrate from one cluster to another to optimize the service location. Resource management is done by an orchestrator, which may interwork with others, controlling neighboring clusters, to migrate services.

use or the transferring of large amounts of data to the cloud would require too much bandwidth;

- augmented reality (AR), and in general extended reality (XR), applications, as well as all six degrees of freedom (6DoF) immersive technology that require both low latency and large data rate;
- ML applications making use of the ML as a service [12] concept, which has indeed emerged as a new paradigm, whereby trained or pre-trained models are provided for making decisions of different type and in different contexts.

d) Orchestrator: To complete the above functions, resource and service orchestration is needed. Resource orchestration can be both reactive (which may sometimes be too late) or proactive, so that resources, and the functions mapped thereon, can naturally follow demand in space and time. We remark that the orchestration itself becomes one of the tasks to be distributed and executed within the virtual edge, similarly in this respect to user applications.

The orchestrator (see Figure 2) has to observe and monitor nodes and their computing and communication resources, and schedule them for current functions and microservices. Machine learning will help to make such decision with little and often impaired information about the available edge components. From an architectural perspective, the orchestrator can be centralized at a (physical) edge server (or even in the cloud, with the risk of additional problems due to the inherent communication delay), or decentralized through hierarchically-coordinated clusters of nodes participating in the V-Edge. In realistic deployments, a partially distributed solution may be preferred for better resilience and responsiveness of the overall system.

e) Architecture: The architecture of a V-Edge system enables the interaction between the above described basic components, as illustrated in Figures 1 and 2. A key feature of the V-Edge architecture is that users are virtually clustered so as to provide resources qualitatively equivalent to the ones provided by the infrastructure. This cluster-based organization

is meant to facilitate and optimize resource management while providing resiliency and flexibility, like done, e.g., in the context of vehicular micro-clouds [10]. Services and network functions can be instantiated in a cluster and then migrated to another one dynamically, under the coordination of the orchestrator, and as a consequence of the learning process that underpins its operations. Figure 2 zooms into the architecture outlining interconnected mobile and infrastructure clusters that are orchestrated together. The distributed nature of all resources additionally requires novel concepts and interfaces for distributed orchestration and for the cooperation between orchestrators, and even between multiple such clusters, edge components, and the back-end cloud servers.

III. KEY TECHNOLOGIES AND RESEARCH CHALLENGES

Existing work on edge computing has predominantly focused on resource allocation on edge servers that may experience dynamic load, but whose deployment is static or only changes on a long time scale. As mentioned, V-Edge goes well beyond and lifts this limitation by allowing also servers to be mobile, thus, computational, storage, and communication resources appear and leave at any time. In this section, we identify the most relevant key technologies that can make V-Edge a reality.

A. Performance Aspects

Similarly to non-virtual edge clouds, a V-Edge system needs to support KPIs such as high throughput, low latency, low service rejection rate, high utilization, short provisioning times, high dependability, and easy management, as well as to maximize the number of satisfied users and expected revenue compared to capital or operational expenditure (CAPEX, OPEX). There exists, however, a differentiating factor between V-Edge and non-virtual edge clouds: the node *churn rate* in the underlying network and the evolution of the network topology in space and time due to devices joining and leaving the V-Edge. Here, churn rate is not a performance metric, rather, a system characteristic with a twofold impact. On the one hand, it may lead to a degradation in the V-Edge KPIs, which could be characterized as the *price of virtuality*; on the other hand, the contribution of mobile devices to the V-Edge allows for significant CAPEX and OPEX savings.

While this is a fair perspective from an end user's or investor's perspective, it can fall short when comparing different V-Edge realizations against each other. First, more fine-grained metrics would be needed in this case to characterize the performance of services as well as management and orchestration systems (e.g., packet latency vs. service initiation time, or traffic throughput vs. number of service deployments per second). Second, suitable metrics should be selected to highlight the existing trade-offs in performance. A typical example is the overhead introduced by state synchronization to ward off service interruptions, compared against the degradation in the users' quality of experience caused by those same service interruptions.

We argue that different trade-offs can be achieved depending upon how a V-Edge is configured, obtaining a Pareto front of optimal trade-offs. Further, as exemplified in Figure 3,

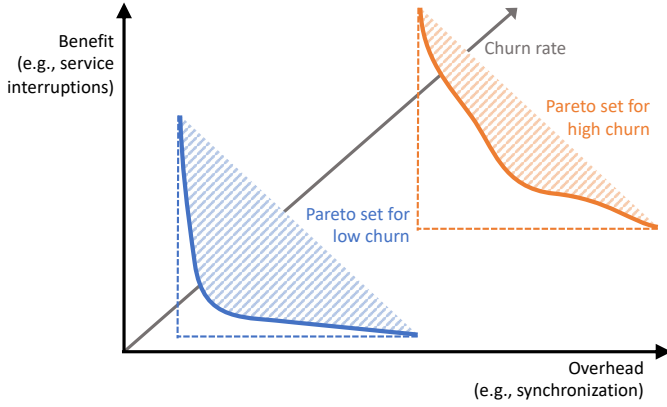


Figure 3. Services KPIs in the context of the V-Edge concept.

different Pareto fronts may emerge for different churn rates and devices' connectivity patterns. Such complex dependencies and entanglement between diverse aspects of the V-Edge cannot be captured through the existing performance metrics; they rather call for a novel, complex notion of “figure of merit”.

B. Orchestration of Microservices

Network softwarization is taking over the data, control, and management planes as well as different protocol layers. Examples of data plane virtualization include virtual routers and user applications, while a relevant control plane example is the O-RAN control of the radio interface. As mentioned in Section II, virtual network functions (VNFs) stemming from such softwarization can be seen as (components of) microservices, which need to be properly and jointly orchestrated whenever they compete for the same physical resources. Further, depending on their type and logic, microservices can be executed in different execution environments with varying trade-offs in terms of capabilities and performance.

Thus, an orchestrator for a V-Edge system needs to provide the same functionality as any of the orchestrators proposed for an ordinary edge infrastructure. Namely, it has to map VNFs from microservices to the available resources, taking into account not only their requirements but also the computing and communication capabilities of the device on which they are mapped and the performance impact of the services that leverage such microservice instances. This is, however, not the only issue a V-Edge orchestrator faces. Indeed, it has to cope with the network and node churn: quickly changing network conditions and node availability. A V-Edge orchestrator has to be aware of this churn as well as of the services' ability to deal or not to deal with it (e.g., stateless vs. stateful services) and their temporal and spatial availability requirements – aspects that are exacerbated in V-Edge with respect to conventional scenarios. This fact invalidates any conventional, long-term approach and demands for a more agile, adaptive solution.

We address this challenge by leveraging ML techniques, conceiving a multi-faceted framework that can effectively deal with the multitude of necessary observations and actions. Specifically, the proposed V-Edge orchestration framework includes:

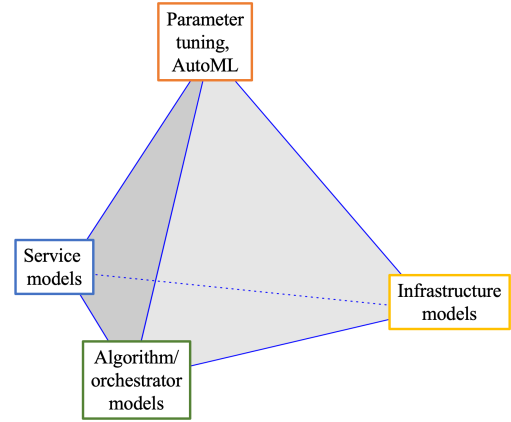


Figure 4. The V-Edge tetrahedron orchestrator (VETO) concept.

- 1) a network model, partially based on explicit information (e.g., battery or computing capacity of a device) and partially learned information (e.g., movement patterns and sojourn time), to account for individual devices' capabilities and behavior;
- 2) a service model, partially provided by the VNF graph composing the service and the VNFs' specifications, partially learned (e.g., how disruption-tolerant is a service, how does a disruption affect the users' quality of experience); we underline that some information that could be provided by the service developer might actually need to be learned in practice and that a continuous update of the service understanding is necessary;
- 3) the orchestrator as such: learning scaling, placement, routing, migration, and other actions based on the network and service models;
- 4) an Auto-ML component: since the above three models need to be continuously trained in the field and since properly parameterizing training is hard, an Auto-ML component is necessary to tune training hyperparameters.

The four components of the framework are connected in a tetrahedron as depicted in Figure 4, as they all depend on each other; we dub such a framework V-Edge tetrahedron orchestrator (VETO). VETO provides a functional separation of a learning-based orchestrator. Some important challenges, however, remain to be addressed for a detailed framework design. In particular, it is critical to: (i) learn correlation between network and service models, e.g., between user spatial distribution and service demand dynamics, (ii) identify the hyperparameters to be learned by the Auto-ML component, (iii) define the time scale over which the different components should operate, (iv) understand with which granularity instances of VETO should be deployed to deal with different geographical areas to make the system scalable.

C. Cooperative Computing

Cloud computing has become extremely popular due to its flexible (cost) structures and dynamic resource allocation; overall, it has been a door opener for many novel services. Edge computing and service placement in close proximity of

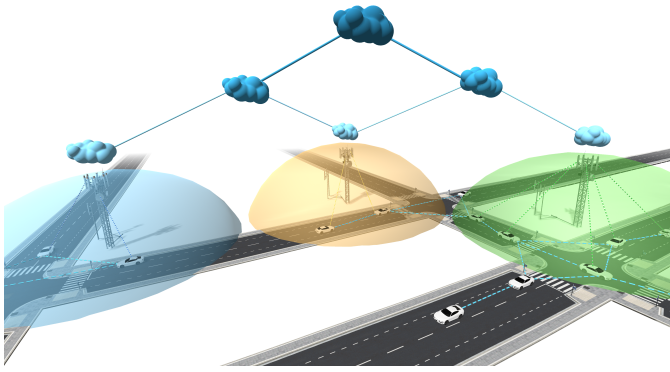


Figure 5. Placement of mobile edge computing for connected vehicles.

the user enabled a new kind of services particularly focusing on low latency and often referred to in the context of the Tactile Internet [7], [8].

However, latency is not only caused by propagation delays. Other factors such as computing delay also play a dominant role so that the optimal placement of a function is not always at the edge [13]. Figure 5 illustrates the problem in the application scenario of connected vehicles, highlighting different placement options. The V-Edge architecture indeed allows for vertical and horizontal placement and distribution of edge infrastructure.

A vital research field is resilience in such agile environments. Virtualization of all edge computing components introduces the risk of service starvation: tasks currently offloaded to virtual edge components may not be completed, or not be completed in time. In communications and storage, replication and redundancy is often used to overcome such problems, and, even though not efficient in terms of resource utilization, this can greatly increase resilience of the system. Recent advances in the field of coding, in particular network coding and coded caching, help achieving efficiency, resilience, and latency at the same time. Unfortunately, these ideas do not immediately apply to computing. Replication has to deal with erroneous feedback information and the state of the cooperative computing instances may diverge. Microservices running on cooperative machines improve resilience, but not efficiency.

Coded computing may provide solutions for cooperative computing [14]. In order to enable cooperative computing in V-Edge, the following phases are to be considered.

- *Phase 0* is about hierarchical mobile edge clouds as described already for vehicular micro clouds [10]. Edge nodes are interconnected in form of clusters in the V-Edge architecture to distribute tasks among themselves using the backend data center as a fallback solution. All relevant meta data describing tasks and associating end users need to be synchronized among all participating nodes in a hierarchical manner.
- *Phase 1* uses a coding-based approach. Similar to network coding for storage and communication, also computing tasks can be coded to avoid outages if physical nodes leave the virtual edge [14]. Coded computing is normally used between neighboring nodes such as mobile robots or cars, but it can be extended to cooperation among multiple

edge clouds, adding resilience and performance.

- In a final *Phase 2*, such coding-based distributed computing will be inherently integrated with new approaches to resource management. Current resource management solutions focus on communication, sometimes also incorporating computational resources, but still in a simplistic way.

For cooperative computing, either explicit communication between participating nodes in the V-Edge or mediation by hierarchies up to the backend data center, or implicit communication by means of inference is needed. Figure 5 illustrates the concept of localized edge clouds interconnected in a hierarchical manner to perform such cooperative computing. Research questions range from the identification of required data, to finding paths the data has to travel along, to data fusion, and compressed sensing. Cooperative computing, of course, has to rely on distributed learning concepts. Here, federated learning will play a dominant role because of its capability to train distributedly and then to merge the resulting models in a privacy preserving manner [11], [15]. The grand challenge here is sparsification of models in order to reduce the overhead resulting from model distribution.

IV. DISCUSSIONS AND CONCLUSION

Revisiting the motivation for our virtual edge computing (V-Edge) approach, in the following we discuss the benefits of this novel architecture and what cannot be done with traditional cloud, MEC, and possibly fog computing. From a paradigmatic point of view, there are many reasons to make use of V-Edge, though some fundamental problems need to be addressed before implementation.

From a *policy perspective*, the V-Edge concept addresses many problems that have hampered (mobile) global communications in the past decades. As discussed above, V-Edge requires necessarily open solutions like O-RAN, or similar ones, at different architectural levels. Openness in telecommunications and computing has proven to be one of the key enablers for innovation and economic growth; thus, the V-Edge vision naturally becomes the melting pot for novel services, solutions, start-ups, and technological evolution. This consideration alone should be enough for all actors, and standardization bodies in particular, to embrace V-Edge and mold future business based on this equitable architecture.

Scalability is a more technical reason to foster V-Edge. 5G/6G architectures, together with computation (think about GPUs) and local access (WiFi 6 and the upcoming WiFi 7), have shown that only extreme distribution and densification of resources can meet the increasing requirements on communications and services. V-Edge is bringing this evidence from subliminal awareness to architectural design, highlighting and formalizing the interdependence between communications, computing, management (resource allocation and scheduling), and service KPIs. So doing, V-Edge clarifies the technical challenges that need to be addressed for success, first of all in the realm of ML, acknowledging that traditional models cannot be applied to a system whose evolution is not predictable *a priori*. It also allows for a level of adaptability and flexibility

that empowers the autonomous evolution of functions, services, and management models through autonomous learning and self-development.

Efficient resource utilization is going hand in hand with scalability to make advanced services more accessible and, thus, affordable by a wider sector of the society. If, on the one hand, a distributed architecture is the only solution to scalability, on the other hand, it is well known that uncoordinated distribution makes an inefficient use of the resources, from storage and computing power, down to communications and energy. V-Edge proposes an advanced, ML-oriented orchestration that enables the efficient and dynamic use of resources, especially leveraging those that go unused for a large part of the time. An example for all: processing power on autonomous vehicles when they are parked. The safety requirements of Society of Automotive Engineers (SAE) Level-5 autonomous driving require a processing power (CPU and GPU) that is comparable to several nodes of high performance computing systems, and this extreme capacity is right there, at the edge, but with traditional architectures it is impossible to tap it.

Finally, *security and privacy* need to be considered, which goes well beyond the scope of this paper. Theoretical computer science indicates that distributed systems are in general safer, more secure, and most of all naturally following the implementation of “privacy by design” principles. V-Edge clearly matches this indication, with its extreme distribution and the orchestration of resources coming from different actors and entities. However, we are also well aware that *practical* systems often fail to meet theoretical results, in particular in the case of security where the complexity of the analysis of distributed systems may lead to design failures, with severe consequences. This is a further topic for research and design towards the V-Edge realization.

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